

The Propulsion & Control of an Autonomous Underwater Vehicle

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Supervisor: Professor Meyer Nahon | Client: McGill Robotics

Objective

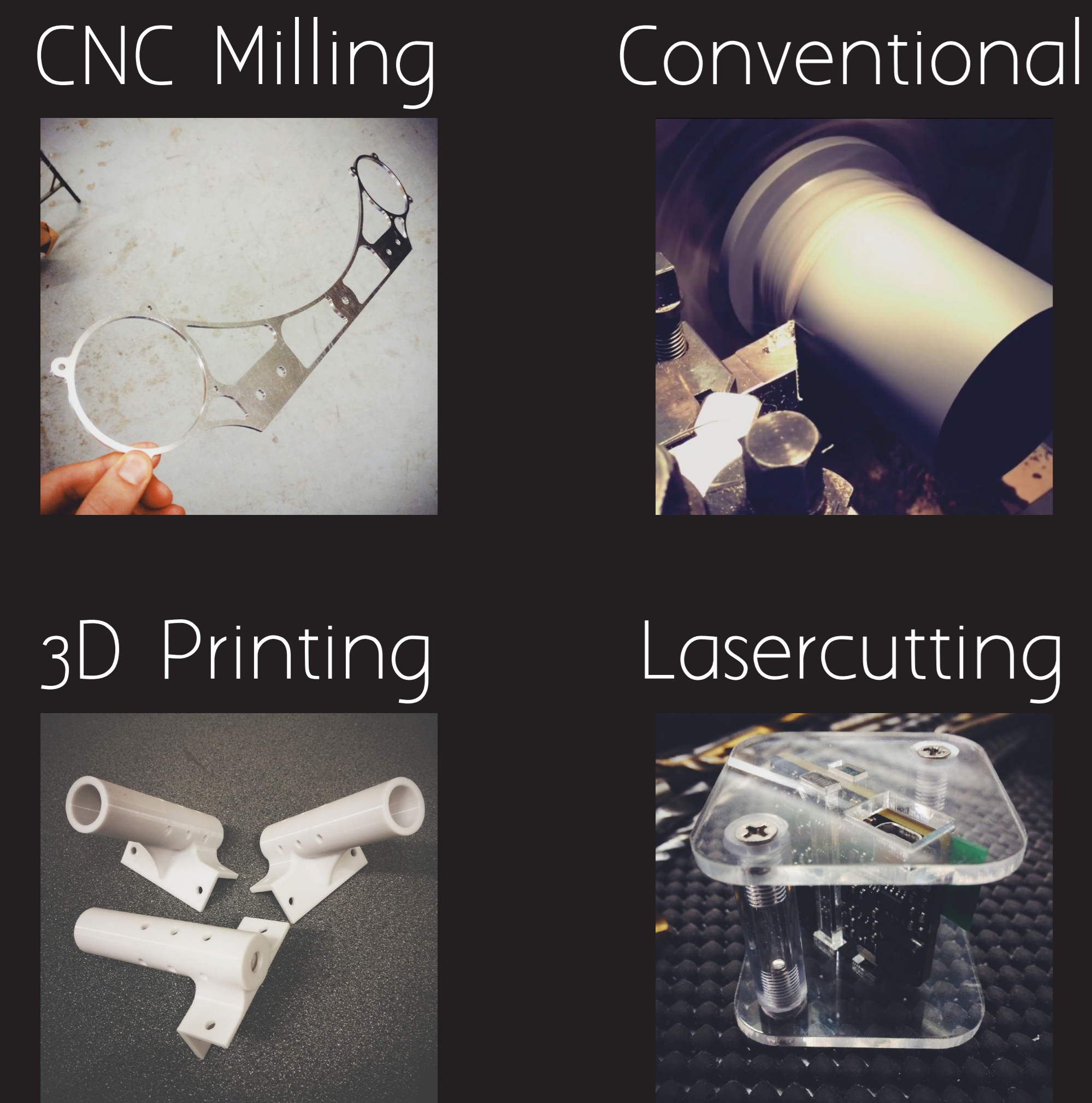
Design and implement the propulsion and control system for an Autonomous Underwater Vehicle

Competition

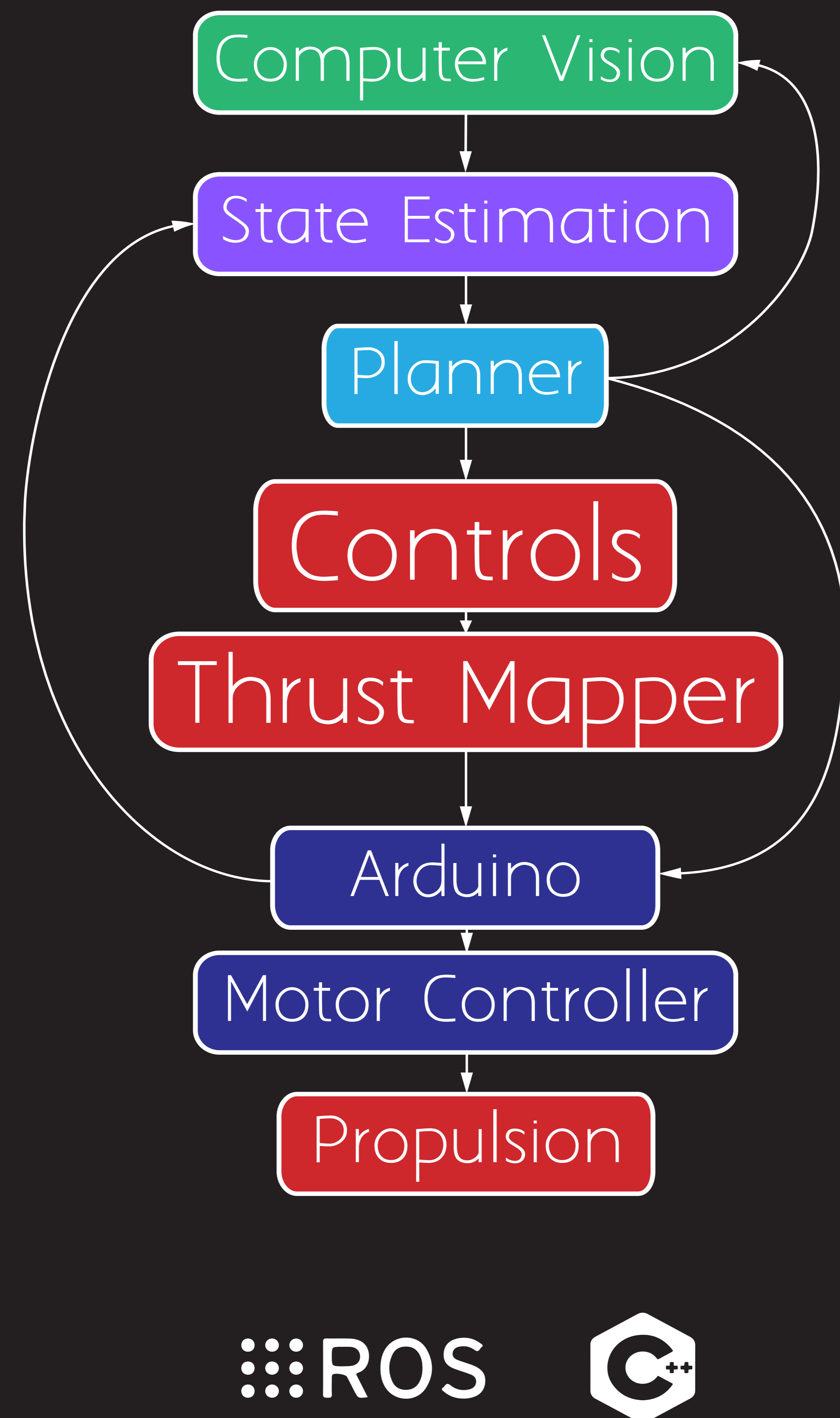


The AUVSI Foundation & ONR's 17th Annual International RoboSub Competition in San Diego, CA

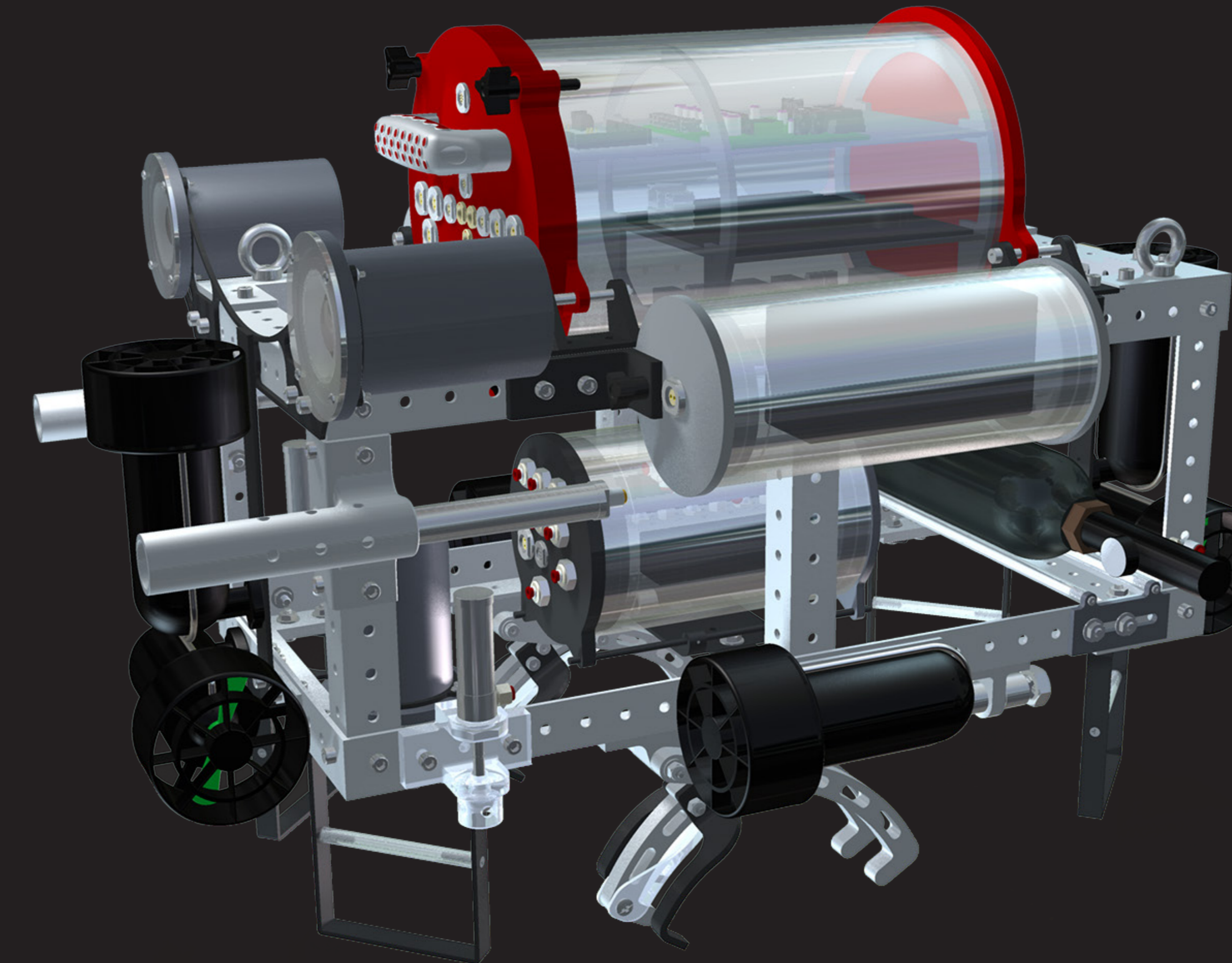
Manufacturing



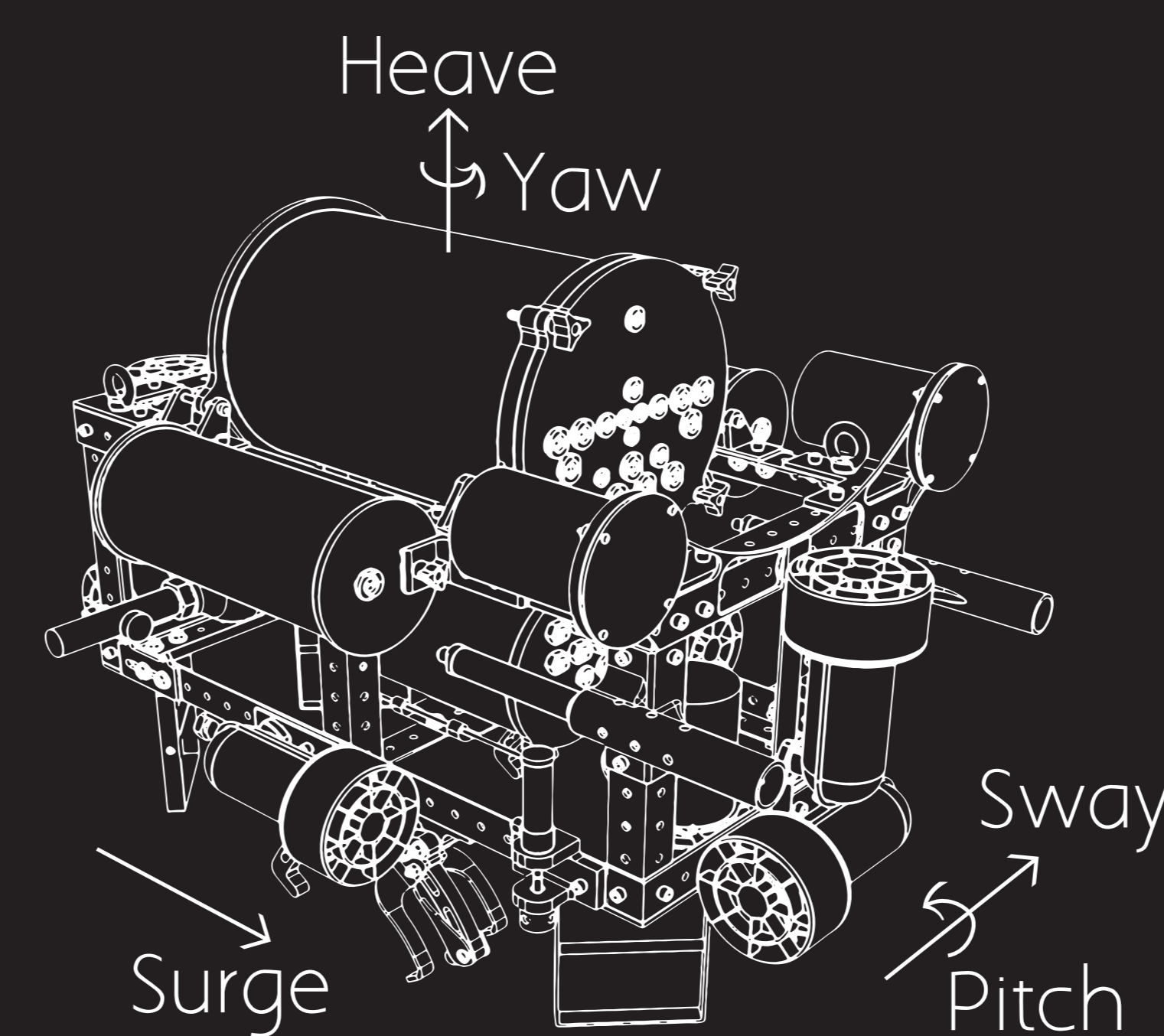
Closed-Loop PID



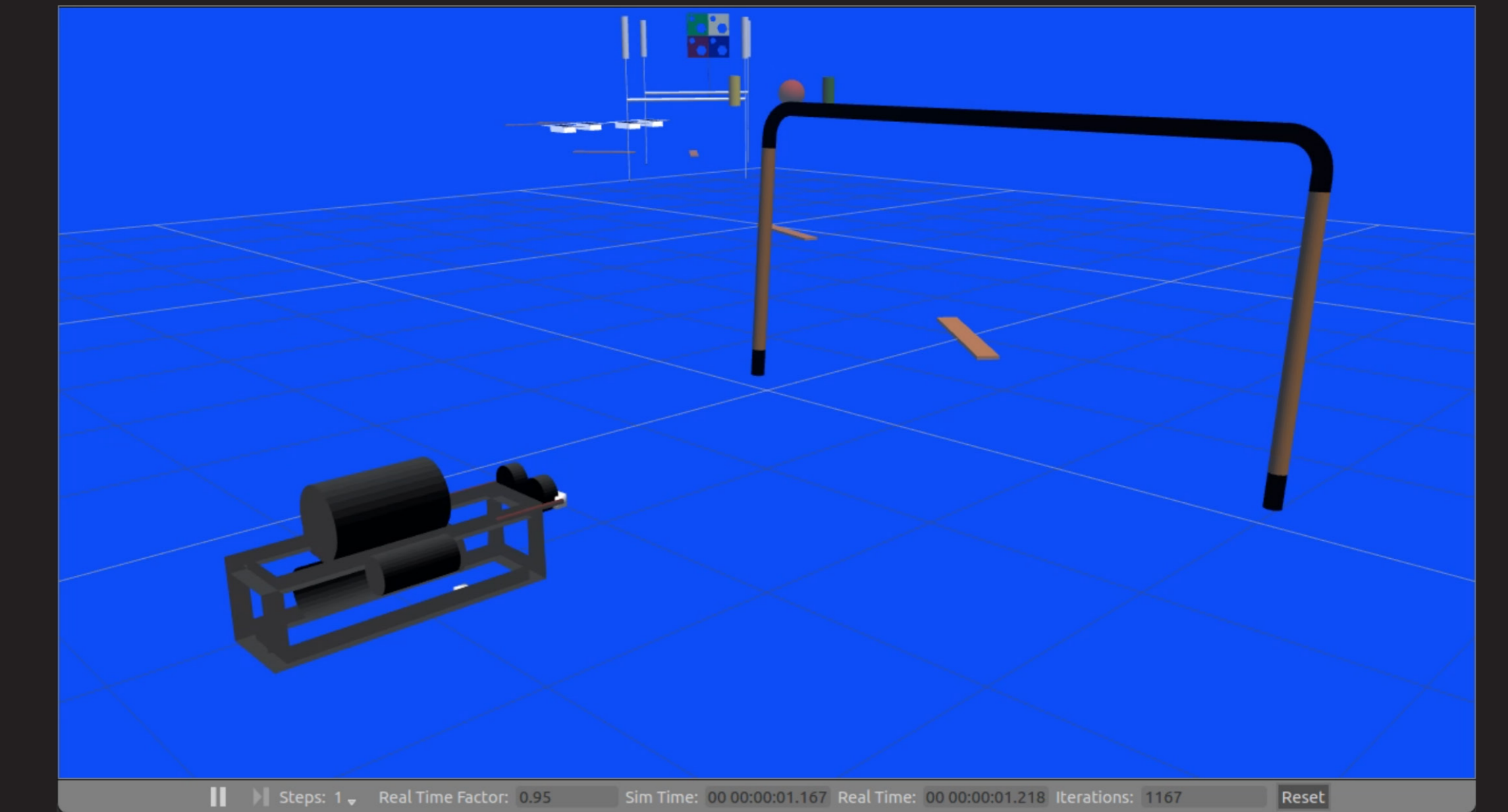
CAD Model



5 DoF Propulsion

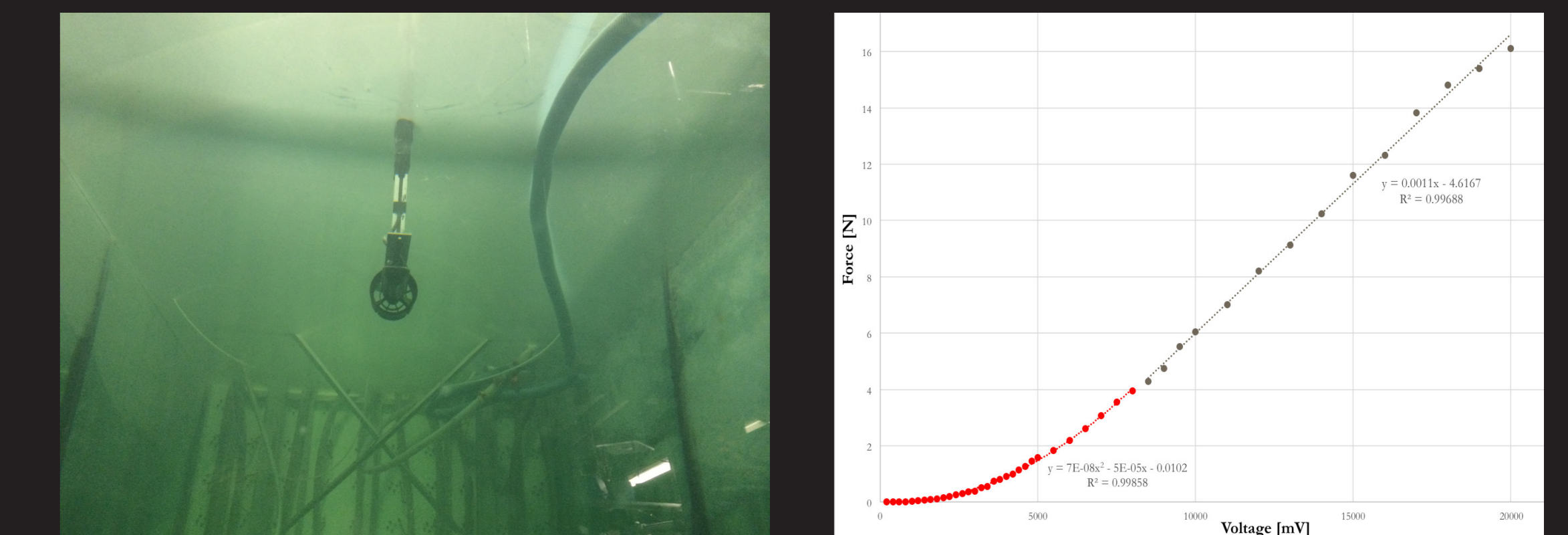


Simulation



Gazebo Simulation Environment

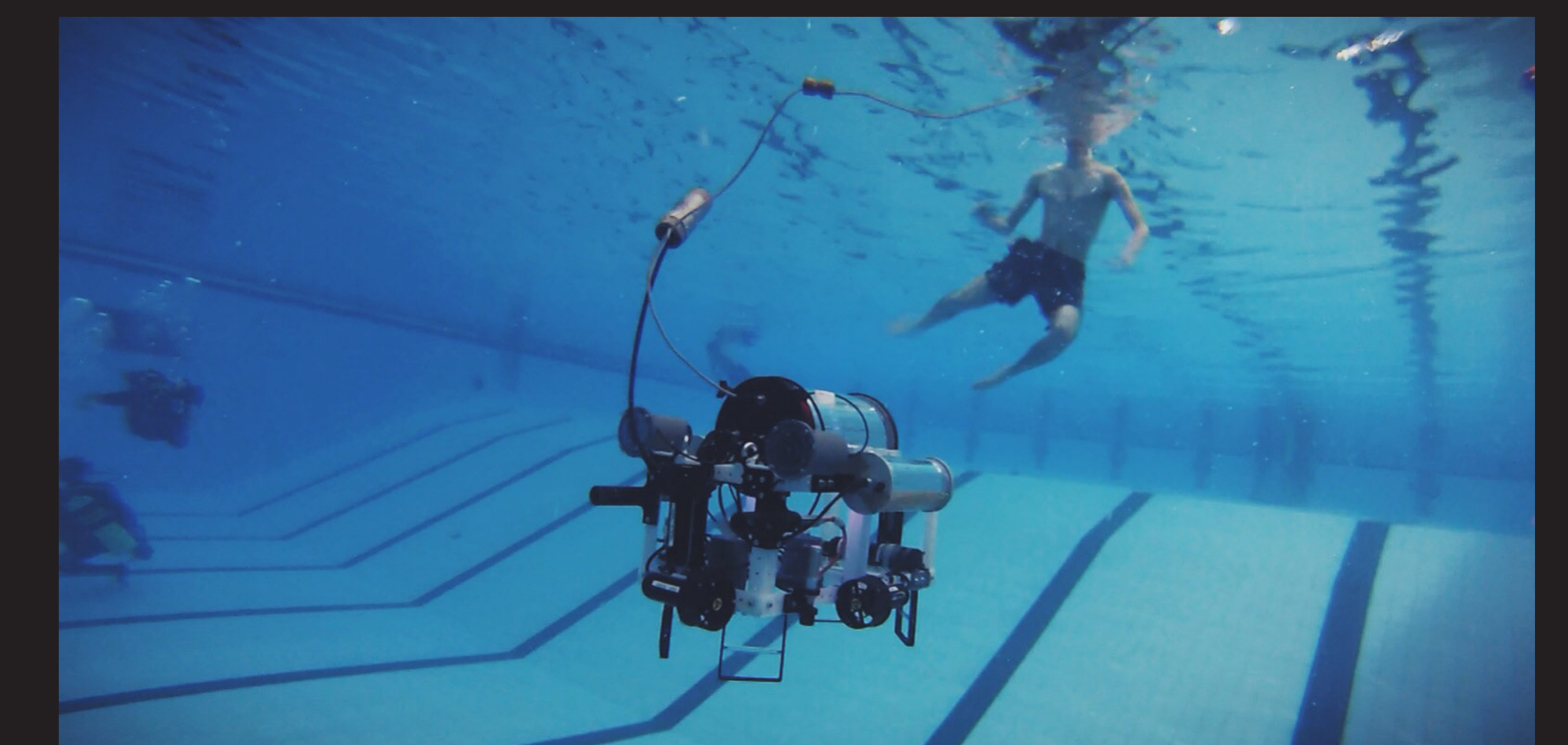
Characterization



Testing Apparatus

Force v. Voltage Curve

Testing



Buoyancy & Control Test in the McGill Pool